Reel evolution at your service: Collaborative robot, call this version - Yaskawa, HC10 palletizer Conveniently design for easy operation by Roboman-pta - using Yaskawa HC10 for highest standard in stability and safety.

- Workspace:
- Pay load:
- Speed mode:
- Collaborate mode $0,25 \mathrm{~m} / \mathrm{sec}$
- Hybrid mode5 times faster
- Customized:
- Gripper
- Software standard
- Soft-touch screen
- Screen guidance
- Vision check
- Laser detection
- Standards
- Benefits
- Collaborate

Hybrid speed

- The best from both worlds
- Customized
- Industrial quality
- Proved and safe
- IPR
$2 x$ euro pallet ( $0,8 \times 1,2$ ) $x$ height 1,2 meters 10 kg
Flexible solution without limits
Safety speed near humans
Speed with security enabled
Optimized for customer use
Magnetic, pneumatic, mechanic
Palletizing select work object dimensions
Operators menu - "what do you want now"
Robots info - "what you should do now"
Designed after your needs, placed in front
Mounted on gripper, find your parts
All Collaborative tools available
When your needs changes
Works with humans
Higher capacity
Collaborative mode and Hybrid speed
Wide range of solutions - at work
Result with nearly 50 years' experience, Yaskawa
In cooperation with Danish Technological institute
3 Patent Pending


Roboman-pta is a company placed in the middle of the geographical robot heart of Denmark:
"\#we are robot heroes"
The product is based on the collaborative platform from the best robot supplier in the world; Yaskawa. Look at the video and be inspired - don't hesitate to call us.

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- it is human to get others to do the work -the robots do not disagree.


## robonna

Solutions with On-Robot or Schunk grippers, ask for more information.



VG10 VACUUM GRIPPER

Simulation: to ensure the right solution, send us a stp-file or similar (your parts), and a small project
description - and we will respond to you


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Human-Collaborative Robot 6 Integrated Torque Sensors


WWw.yaskiwa.gu.com

MOTOMAN HC10 is a 6 axes human-colaborative robot with a payload of up to 10 kg . Operator's safoly la assurad by a Fower and Force Uimk tachnology that slopa the robot in case of contact with an operzior.
The robot arm can be hand gulded by an operator and robot poallona and gripper oparatlon can be raglatarad via so called "Easy Tapching Bwitich Box". Thase 1aatures otlar time saving during the robot prograrroring. The robots arm geometry was designed to avoid pinch pointa [finger].
The MOTOMAN HC10 robot can operabe without addilional profective maasures lice a safety fance, dopending on the ribk asaessment. Tha sawes qpace and coats. Its instaliation aroa is very fiexibla and thersiore able to oparate at difforant workplaces.

## KEY BENEFIT8

## Controller

- Fuly industrial robot comirollar
- YRC1000 for HC10 and HC-10DT
- YRC1000micro for HC10DT


## High safety

- Comiact force betwaen operator and robot in Imiliad
to a safo leval
- Arrn goomatry dosigned to awold pinch points
(finger protaction)
- Eadaty standards-applcafiona for Induatital robota: 100 10218-1 [5.10.5 Fowar and Force limiling
- Comples to 180 T8 15066
- Badaty functiona industrial robot controliar:

190 13B49-1, FLd, Cuil 3

* Functlonal Bafaty Unit Includad


## Eavy teaching

* Mowa the robot arm directly via hand guiding function: assy taaching mode with a switch box


## No safoty fence

* Dapanding on the application, the HC10 can be used without a gataly fance


## robonna <br> handling \& welding

MOTOMAN HCHODT


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